

A formal explication of the search for explanations. The adaptive logics approach to abductive reasoning.

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MBR'09 December 17–20 2009, Campinas

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Outline

Searching for Explanations

- Abduction?
- Logic–Based Approaches to Abduction
- Aim of this Talk
- 2 The Deductive Frame
 - Abduction vs Deduction
 - A Modal Frame
 - Representing Abductive Reasoning Contexts
- On Defeasible Inference
- Enter Adaptive Logics
 - Multiple Abduction Processes
 - General Characterization
 - Proof Theory
 - Examples



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Searching for Explanations

Backwards reasoning: from the phenomena to be explained to possible explanations.



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 \Rightarrow Abductive inferences

 $A \supset B, B \vdash A$ (Affirming the Consequent)



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⇒ Abductive inferences

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Example

- A physician in search of the right diagnosis for a patient's symptoms,
- a technician trying to find out why a machine broke down,
- a scientist trying to find an explanation for an empirical phenomenon contradicting some predictions derived from an accepted theory,...



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A number of conditions is specified that enable one to decide whether or not a particular abductive inference is sound.



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Example

Given the background theory Γ , A is an explanation for B iff

- $\Gamma \cup \{A\} \vdash B$
- Г ⊬ ¬А
- Γ ⊬ B; A ⊬ B
- ...



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 - FOR FOCUS is on abductive consequence, not on abductive reasoning



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Backwards Deduction plus Additional Conditions

A number of conditions is specified that enable one to decide whether or not a particular abductive inference is sound.

- \neq a realistic explication of abductive reasoning
 - FOR Focus is on abductive consequence, not on abductive reasoning
 - \Rightarrow Search procedures instead of a proof theory
 - e.g. Tableau methods (Aliseda–Llera 2006, Mayer&Pirri 1993)



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Advantages

- (Some of) the conditions of **BD** can be incorporated.
- A nice proof theory for abductive reasoning is provided.



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- A nice proof theory for abductive reasoning is provided.



⇒ The adaptive logics approach provides a more realistic explication of the application of abductive inferences in human reasoning!

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To present a general approach towards the explication of abductive reasoning based on the Adaptive Logics Programme.



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To present a general approach towards the explication of abductive reasoning based on the Adaptive Logics Programme.

Three Steps

- The deductive frame
 - = To spell out the relation between abduction and deduction.
- On defeasible inference
 - = To characterize the abductive inference rule in general.
- Enter adaptive logics
 - = To characterize some adaptive logics for abductive reasoning.



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Abduction vs Deduction

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 Abductive reasoning validates some arguments that are not deductively valid.

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- Abductive reasoning is constrained by deductive reasoning.
 - FOR Abductive consequences of a premise set might have to be withdrawn in view of its deductive consequences.
 - ⇒ Abductive inference steps are applied against a deductive background!



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Language Schema of RBK					
	language	letters	logical symbols	set of formulas	
	\mathcal{L}	S	$\neg, \land, \lor, \supset$	\mathcal{W}	
	$\mathcal{L}^{\mathcal{M}}$	S	$\neg, \land, \lor, \supset$ $\neg, \land, \lor, \supset, \Box_n, \Box_e, \Diamond_n, \diamond_e$	$\mathcal{W}^{\mathcal{M}}$	
• \Box_n expresses nomological necessity.					
• \Box_e expresses <i>empirical necessity</i> .					

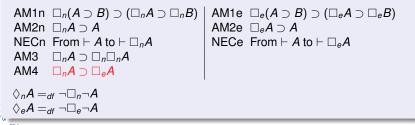
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Proof Theory of **RBK**

= the axiom system of CL, extended by



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Situations in which people search for possible explanations for some puzzling (empirical) phenomena.



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$$\mathcal{W}^{\mathcal{N}} = \{ \Box_n A \mid A \in \mathcal{W} \}$$
$$\mathcal{W}^{\mathcal{E}} = \{ \Box_e A \mid A \in \mathcal{S} \cup \mathcal{S}^{\neg} \}$$

Nomological Facts Empirical Facts



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- = The background knowledge
 - ⇒ Necessities express *contextual certainty*!



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AC in a Modal Environment

The applications of **AC** that qualify for conditional acceptance are limited to those satisfying the following schema:

AC^m $\Box_n(A \supset B), B, \Delta \vdash A$



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OTHERWISE It wouldn't be in need of an explanation.

 Certain additional conditions have to be fulfilled before AC^m may be applied.

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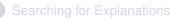
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- \Rightarrow These defeasible inference rules are prior to **AC**^m.
- ⇒ Abduction processes are layered processes!
 - ⇒ The adaptive logics needed are *prioritized adaptive logics*.

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Practical Abduction

In case of multiple possible explanations, only the disjunction of all possible explanations is derivable.

⇒ The logic AbL^p



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Theoretical Abduction

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Prioritized Abduction

In case of multiple possible explanations, only the most plausible explanations are derivable.



⇒ The logic AbL^{pt}

Earlier Attempts



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BUT Some extra-logical features are incorporated.

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- J. Meheus and D. Batens. A formal logic for abductive reasoning. *Logic Journal of the IGPL*, vol. 14, 2006, pp. 221–236.
 - BUT Only abductive inferences at the predicate level.
 - BUT Only practical abduction could be characterized.
 - \Rightarrow Abductive reasoning is captured in a limited way.



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Enter Adaptive Logics

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Prioritized Adaptive Logics



Prioritized Adaptive Logics

- 1. A Lower Limit Logic (LLL)
 - The LLL determines the inference rules that can be applied unrestrictedly.
- 2. A Set of Abnormalities ($\Omega = \Omega_0 > \Omega_1 > ... > \Omega_n$)
 - Elements of Ω are interpreted as false as much as possible
 The result: some conditionally derived consequences

$\frac{A \vee B^{-a}}{A}$, unless B cannot be interpreted as false

- Prioritized: Ω is a structurally ordered set of sets.
 - Consequences obtained by falsifying abnormalities of a certain priority may necessitate the withdrawal of consequences obtained by falsifying abnormalities of a lower priority.

3. An Adaptive Strategy



The adaptive strategy determines which of the conditionally derived formulas have to be withdrawn.

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The Adaptive Logic AbL^p



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• $\Omega_p = \{ \Box_n(A \supset B) \land B \land \neg \Box_e B \land \neg A \mid$

$$B \in S \cup S',$$

- A in Conjunctive Normal Form, and
- B is not a subformula of A



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• $\Omega_p = \{ \Box_n (A \supset B) \land B \land \neg \Box_e B \land \neg A \mid B \subseteq S \mid \downarrow S]$

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3. Adaptive Strategy = Reliability



The Adaptive Logic AbL^t



H. Lycke (Ghent University)

The adaptive logics approach to abductive reasoning

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General Characterization: Theoretical Abduction

The Adaptive Logic AbL^t

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$$\triangleright \quad A_1,...,A_n,B\in \mathcal{S}\cup \mathcal{S}^\neg,$$

▷ *B* is not a subformula of $A_1 \land ... \land A_n$, and



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$$\Omega = \Omega_{bk} > \Omega_t$$

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 $\land \neg (A_1 \land \dots \land A_n) \mid$
• $A_1, \dots, A_n, B \in S \cup S^{\neg},$
• B is not a subformula of $A_1 \land \dots \land A_n$, and
• $\neg [A_1^n \supset B] =_{df} \neg \Box_n((A_2 \land \dots \land A_n) \supset B) \land$
 $\neg \Box_n((A_1 \land A_3 \land \dots \land A_n) \supset B) \land$
 $\dots \land \neg \Box_n((A_1 \land \dots \land A_{n-1}) \supset B)$

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By integrating the knowledge of priorities in the background knowledge.



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By integrating the knowledge of priorities in the background knowledge.

- $\Rightarrow \text{ If } \Box_n(A \supset B) \text{ then } \Box_n \Diamond_e ... \Diamond_e(A \land B) \text{ expresses that}$
 - A is a possible explanation of B, and
 - the lesser ◊_e's, the more plausible A is as an explanation of B.



How to Represent Priorities?

By integrating the knowledge of priorities in the background knowledge.

- $\Rightarrow \text{ If } \Box_n(A \supset B) \text{ then } \Box_n \Diamond_e ... \Diamond_e(A \land B) \text{ expresses that}$
 - A is a possible explanation of B, and
 - the lesser ◊_e's, the more plausible A is as an explanation of B.

How to Make Use of Priorities?

There are multiple possibilities!

HERE in a straightforward way.



The Adaptive Logic AbL^{pt}



The Adaptive Logic AbL^{pt}

- Lower Limit Logic (LLL) = the logic RBK 1.
- 2. Set of Abnormalities $\Omega = \Omega_{bk} > \Omega_{pt_1} > \Omega_{pp_1} > \Omega_{pt_2} > \Omega_{pp_2} > ... > \Omega_t$
 - Ω_{bk} and Ω_t as for theoretical abduction.

•
$$\Omega_{pt_i} =$$





Adaptive Strategy = Reliability 3.

H. Lycke (Ghent University)

MBR'09, Campinas

31/42

The Adaptive Logic AbL^{pt}

- 1. Lower Limit Logic (LLL) = the logic **RBK**
- 2. Set of Abnormalities $\Omega = \Omega_{bk} > \Omega_{\rho t_1} > \Omega_{\rho p_1} > \Omega_{\rho t_2} > \Omega_{\rho p_2} > ... > \Omega_t$
 - Ω_{bk} and Ω_t as for theoretical abduction.
 - $\Omega_{pt_i} = \{ \Box_n((A_1 \land \dots \land A_n) \supset B) \land \Box_n \Diamond_e^i((A_1 \land \dots \land A_n) \land B) \land B \land \neg \Box_e B \land \neg (A_1 \land \dots \land A_n) \land \neg [A_1^n \supset B] |$
 - ▷ For the most part as for theoretical abduction, except for



3. Adaptive Strategy = Reliability

• $\Omega_{nn_i} =$

The Adaptive Logic AbL^{pt}

- 1. Lower Limit Logic (LLL) = the logic **RBK**
- 2. Set of Abnormalities $\Omega = \Omega_{bk} > \Omega_{\rho t_1} > \Omega_{\rho p_1} > \Omega_{\rho t_2} > \Omega_{\rho p_2} > ... > \Omega_t$
 - Ω_{bk} and Ω_t as for theoretical abduction.

i times

•
$$\Omega_{pt_i} = \{ \Box_n((A_1 \land ... \land A_n) \supset B) \land \Box_n \Diamond_{e}^i((A_1 \land ... \land A_n) \land B) \land B \land \neg \Box_{e} B \land \neg (A_1 \land ... \land A_n) \land \neg [A_1^n \supset B] |$$

For the most part as for theoretical abduction, except for

$$= \Box_n \underbrace{\diamond_e} \ldots \underbrace{\diamond_e} ((A_1 \land \ldots \land A_n) \land B)$$

3. Adaptive Strategy = Reliability

 $\Omega_{nn_i} =$

The Adaptive Logic AbL^{pt}

- 1. Lower Limit Logic (LLL) = the logic **RBK**
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•
$$\Omega_{pt_i} = \{ \Box_n((A_1 \land \ldots \land A_n) \supset B) \land \Box_n \Diamond_e^i((A_1 \land \ldots \land A_n) \land B) \land B \land \neg \Box_e B \land \neg (A_1 \land \ldots \land A_n) \land \neg [A_1^n \supset B] |$$

▷ For the most part as for theoretical abduction, except for

$$= \Box_n \underbrace{\Diamond_e \dots \Diamond_e}_{i \text{ times}} ((A_1 \land \dots \land A_n) \land B)$$

• $\Omega_{\rho\rho_i} = \{ \Box_n((A_1 \land ... \land A_n) \supset B) \land \Box_n \Diamond_e^i((C_1 \land ... \land C_m) \land B) \land B \land \neg \Box_e B \land \neg (A_1 \land ... \land A_n) |$

▷ For the most part as for theoretical abduction, except

The Adaptive Logic AbL^{pt}

- 1. Lower Limit Logic (LLL) = the logic **RBK**
- 2. Set of Abnormalities $\Omega = \Omega_{bk} > \Omega_{\rho t_1} > \Omega_{\rho p_1} > \Omega_{\rho t_2} > \Omega_{\rho p_2} > ... > \Omega_t$
 - Ω_{bk} and Ω_t as for theoretical abduction.

•
$$\Omega_{pt_i} = \{ \Box_n((A_1 \land ... \land A_n) \supset B) \land \Box_n \Diamond_{\theta}^i((A_1 \land ... \land A_n) \land B) \land B \land \neg \Box_{\theta} B \land \neg (A_1 \land ... \land A_n) \land \neg [A_1^n \supset B] |$$

For the most part as for theoretical abduction, except for

$$\square_n \underbrace{\Diamond_e \dots \Diamond_e}_{i \text{ times}} ((A_1 \land \dots \land A_n) \land B)$$

•
$$\Omega_{pp_i} = \{ \Box_n((A_1 \land ... \land A_n) \supset B) \land \Box_n \diamondsuit_e^i((C_1 \land ... \land C_m) \land B) \land B \land \neg \Box_e B \land \neg (A_1 \land ... \land A_n) \mid$$

For the most part as for theoretical abduction, except

> that ¬[
$$A_1^n ⊃ B$$
] is absent, and

• that
$$C_1, ..., C_m \in \{A_1, ..., A_n\}$$

Outline



- Abduction?
- Logic–Based Approaches to Abduction
- Aim of this Talk
- 2 The Deductive Frame
 - Abduction vs Deduction
 - A Modal Frame
 - Representing Abductive Reasoning Contexts
- On Defeasible Inference
- 4

Enter Adaptive Logics

- Multiple Abduction Processes
- General Characterization
- Proof Theory
- Examples



- An AbL^x-proof is a succession of stages, each consisting of a sequence of lines.
 - Adding a line to a proof is to move on to a next stage.



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 - a formula,
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 - an adaptive condition (= a set of abnormalities)



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- Marking Criterium



- As all AbL^x are based on the same adaptive strategy, the marking criterium is the same for all of them.
- Dynamic proofs

Dab–Formulas

 $Dab^{x}(\Delta) = \bigvee (\Delta)$, with $\Delta \subset \Omega_{x}$



Dab-Formulas $Dab^{x}(\Delta) = \bigvee (\Delta), \text{ with } \Delta \subset \Omega_{x}$

Deduct	ion Rules		
PREM	If $A \in \Gamma$:	<u> </u>	Ø
RU	If $A_1, \ldots, A_n \vdash_{RBK} B$:	A ₁ :	Δ ₁ :
			Δ_n $\Delta_1 \cup \ldots \cup \Delta_n$
RC	If $A_1, \ldots, A_n \vdash_{RBK} B \lor Dab^x(\Theta)$	<i>A</i> ₁	Δ ₁
			\vdots Δ_n $\Delta_1 \cup \ldots \cup \Delta_n \cup \Theta$

Minimal Dab^x-consequences

 $Dab^{x}(\Delta)$ is a minimal Dab^{x} -consequence of Γ at stage *s* of a proof, iff (1) it occurs on an unmarked line at stage *s*, (2) all members of its adaptive condition belong to a $\Omega_{x'}$ such that $\Omega_{x'} > \Omega_{x}$, and (3) there is no $\Delta' \subset \Delta$ for which the same applies.



Minimal *Dab^x*–consequences

 $Dab^{x}(\Delta)$ is a minimal Dab^{x} -consequence of Γ at stage *s* of a proof, iff (1) it occurs on an unmarked line at stage *s*, (2) all members of its adaptive condition belong to a $\Omega_{x'}$ such that $\Omega_{x'} > \Omega_{x}$, and (3) there is no $\Delta' \subset \Delta$ for which the same applies.

The Set of Unreliable Formulas of a Certain Priority

 $U_s^x(\Gamma) = \Delta_1 \cup \Delta_2 \cup ...$ for $Dab^x(\Delta_1)$, $Dab^x(\Delta_2)$,... the minimal Dab^x -consequences of Γ at stage *s* of the proof.



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Marking Definition

Line *i* is marked at stage *s* of the proof iff, where Δ is its condition, $\Delta \cap U_s^x(\Gamma) \neq \emptyset$.



Minimal *Dab^x*–consequences

 $Dab^{x}(\Delta)$ is a minimal Dab^{x} -consequence of Γ at stage *s* of a proof, iff (1) it occurs on an unmarked line at stage *s*, (2) all members of its adaptive condition belong to a $\Omega_{x'}$ such that $\Omega_{x'} > \Omega_{x}$, and (3) there is no $\Delta' \subset \Delta$ for which the same applies.

The Set of Unreliable Formulas of a Certain Priority $U_s^x(\Gamma) = \Delta_1 \cup \Delta_2 \cup ...$ for $Dab^x(\Delta_1)$, $Dab^x(\Delta_2)$,... the minimal Dab^x -consequences of Γ at stage *s* of the proof.

Marking Definition

Line *i* is marked at stage *s* of the proof iff, where Δ is its condition, $\Delta \cap U_s^x(\Gamma) \neq \emptyset$.



Marking Proceeds Stepwise

First for the highest priority level, and afterwards for the lower ones.

H. Lycke (Ghent University)

Derivability

A is derived from Γ at stage s of a proof iff A is the second element of an unmarked line at stage s.



Derivability

A is derived from Γ at stage s of a proof iff A is the second element of an unmarked line at stage s.

Final Derivability

A is finally derived from Γ on a line *i* of a proof at stage s iff (i) A is the second element of line *i*, (ii) line *i* is not marked at stage s, and (iii) every extension of the proof in which line *i* is marked may be further extended in such a way that line *i* is unmarked.

• $\Gamma \vdash_{AbL^{*}} A$ iff A is finally derived on a line of a proof from Γ .



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Definition $\langle A, B \rangle =_{df} \Box_n (A \supset B) \land B \land \neg \Box_e B \land \neg A$



Definition $\langle A, B \rangle =_{df} \Box_n (A \supset B) \land B \land \neg \Box_e B \land \neg A$

Example	
---------	--

1	$\Box_n(p \supset q)$	−;PREM Ø)
2	$\Box_n(r \supset q)$	−;PREM Ø)
3	q	−;PREM Ø)

$$\begin{array}{l} U_3^{bk}(\Gamma) = \{ \Box_n(p \supset q), \Box_n(r \supset q) \} \\ U_3^p(\Gamma) = \emptyset \end{array}$$

Definition $\langle A, B \rangle =_{df} \Box_n (A \supset B) \land B \land \neg \Box_e B \land \neg A$

E	Example					
1 2 3 4 5 6	$ \Box_n(p \supset q) \Box_n(r \supset q) q \neg \Box_e q p r $	-;PREM -;PREM -;PREM -;RC 1, 3, 4;RC 2, 3, 4;RC				

Set of Unreliable Formulas $U_6^{bk}(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\}$ $U_6^p(\Gamma) = \emptyset$

Definition

 $\langle A, B \rangle =_{df} \Box_n (A \supset B) \land B \land \neg \Box_e B \land \neg A$

Ex	Example				
1 2 3 4 5 6 7 8	$ \begin{array}{c} \Box_n(p \supset q) \\ \Box_n(r \supset q) \\ q \\ \neg \Box_e q \\ p \\ r \\ \langle p, q \rangle \lor \langle r \land \neg p, q \rangle \\ \langle r, q \rangle \lor \langle p \land \neg r, q \rangle \end{array} $	-;PREM -;PREM -;PREM -;RC 1,3,4;RC 2,3,4;RC 1,2,3,4;RU 1,2,3,4;RU			

Set of Unreliable Formulas $U_8^{bk}(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\}$ $U_8^p(\Gamma) = \{\langle p, q \rangle, \langle r \land \neg p, q \rangle, \langle r, q \rangle, \langle p \land \neg r, q \rangle\}$

Definition

 $\langle A, B \rangle =_{df} \Box_n (A \supset B) \land B \land \neg \Box_e B \land \neg A$

Example				
$ \begin{array}{rcl} 1 & \Box_n(p \supset q) \\ 2 & \Box_n(r \supset q) \\ 3 & q \\ 4 & \neg \Box_e q \\ 5 & p \\ 6 & r \\ 7 & \langle p, q \rangle \lor \langle r \land \neg p, q \rangle \\ 8 & \langle r, q \rangle \lor \langle p \land \neg r, q \rangle \end{array} $	-;PREM -;PREM -;PREM -;RC 1,3,4;RC 2,3,4;RC 1,2,3,4;RU 1,2,3,4;RU 1,2,3,4;RU	\emptyset \emptyset $\{\Box_e q\}$ $\{\Box_e q, \langle p, q \rangle\}$ $\{\Box_e q, \langle r, q \rangle\}$ $\{\Box_e q\}$ $\{\Box_e q\}$	√ √	

Set of Unreliable Formulas

$$U_8^{bk}(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\}$$

$$U_8^p(\Gamma) = \{\langle p, q \rangle, \langle r \land \neg p, q \rangle, \langle r, q \rangle, \langle p \land \neg r, q \rangle\}$$

Definition

 $\langle A, B \rangle =_{df} \Box_n (A \supset B) \land B \land \neg \Box_e B \land \neg A$

E	Example					
1 2 3 4 5 6 7 8 9	$ \begin{array}{c} \square_n(p \supset q) \\ \square_n(r \supset q) \\ q \\ \neg \square_e q \\ p \\ r \\ \langle p, q \rangle \lor \langle r \land \neg p, q \rangle \\ \langle r, q \rangle \lor \langle p \land \neg r, q \rangle \\ p \lor r \end{array} $	-;PREM -;PREM -;PREM -;RC 1,3,4;RC 2,3,4;RC 1,2,3,4;RU 1,2,3,4;RU 1,2,3,4;RU 1,2,3,4;RC	$ \emptyset \emptyset \{\Box_e q\} \{\Box_e q, \langle p, q \rangle \} \{\Box_e q, \langle r, q \rangle \} \{\Box_e q\} \{\Box_e q\} \{\Box_e q\} \{\Box_e q, \langle p \lor r, q \rangle \} $	√ √		

Set of Unreliable Formulas $U_{9}^{bk}(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\}$ $U_{9}^{p}(\Gamma) = \{\langle p, q \rangle, \langle r \land \neg p, q \rangle, \langle r, q \rangle, \langle p \land \neg r, q \rangle\}$

Definition

 $\langle A_1 \wedge ... \wedge A_n, B \rangle =_{df} \Box_n((A_1 \wedge ... \wedge A_n) \supset B) \wedge B \wedge \neg \Box_e B \wedge \neg A \wedge \neg [A_1^n \supset B]$



< (17) > < (17) > >

Definition

 $\langle A_1 \wedge ... \wedge A_n, B \rangle =_{df} \Box_n((A_1 \wedge ... \wedge A_n) \supset B) \wedge B \wedge \neg \Box_e B \wedge \neg A \wedge \neg [A_1^n \supset B]$

Example

1	$\Box_n(p \supset q)$	–;PREM	Ø
2	$\Box_n(r \supset q)$	–;PREM	Ø
3	q	–;PREM	Ø

Set of Unreliable Formulas

$$U_3^{bk}(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\} \\ U_3^t(\Gamma) = \emptyset$$

A (1) > (1) > (2) > (2) > (2)

Definition $\langle A_1 \wedge ... \wedge A_n, B \rangle =_{df} \Box_n((A_1 \wedge ... \wedge A_n) \supset B) \wedge B \wedge \neg \Box_e B \wedge \neg A \wedge \neg [A_1^n \supset B]$ Example $\Box_n(p \supset q)$ -:PREM Ø 1 2 $\Box_n(r \supset q)$ -:PREM Ø 3 -:PREM Ø q 4 р 1,3;RC { $\Box_e q, \Box_n q, \langle p, q \rangle$ } 5 r 2.3;RC { $\Box_e q, \Box_n q, \langle r, q \rangle$ }

Set of Unreliable Formulas $U_5^{bk}(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\}$ $U_5^t(\Gamma) = \emptyset$

Definition

 $\langle A_1 \wedge ... \wedge A_n, B \rangle =_{df} \Box_n((A_1 \wedge ... \wedge A_n) \supset B) \wedge B \wedge \neg \Box_e B \wedge \neg A \wedge \neg [A_1^n \supset B]$

Example $\Box_n(p \supset q)$ -:PREM Ø 1 2 $\Box_n(r \supset q)$ -:PREM Ø 3 -:PREM Ø q 4 1,3;RC { $\Box_e q, \Box_n q, \langle p, q \rangle$ } р 5 2,3;RC { $\Box_e q, \Box_n q, \langle r, q \rangle$ } 6 $\langle p,q \rangle \lor \langle r \land \neg p,q \rangle$ 1,2,3;RC $\{\Box_e q, \Box_n q, \Box_n (r \supset q), \Box_n (\neg p \supset q)\}$ 7 $\langle r, q \rangle \lor \langle p \land \neg r, q \rangle$ 1,2,3;RC { $\Box_e q, \Box_n q, \Box_n (p \supset q), \Box_n (\neg r \supset q)$ }

Set of Unreliable Formulas

$$U_7^{bk}(\Gamma) = \{ \Box_n(p \supset q), \Box_n(r \supset q) \} \\ U_7^t(\Gamma) = \{ \langle p, q \rangle, \langle r \land \neg p, q \rangle, \langle r, q \rangle, \langle p \land \neg r, q \rangle \}$$

$\begin{array}{l} \hline \textbf{Definition} \\ \langle A_1 \wedge ... \wedge A_n, B \rangle =_{df} \Box_n((A_1 \wedge ... \wedge A_n) \supset B) \wedge B \wedge \neg \Box_e B \wedge \neg A \wedge \neg [A_1^n \supset B] \end{array}$

E	Example				
1 2 3 4 5 6 7	$egin{aligned} & \Box_n(p \supset q) \ & \Box_n(r \supset q) \ & q \ & p \ & r \ & \langle p,q angle \lor \langle r \land \neg p,q angle \ & \langle r,q angle \lor \langle p \land \neg r,q angle \end{aligned}$	-;PREM 1,3;RC 2,3;RC 1,2,3;RC			

Set of Unreliable Formulas

```
U_7^{bk}(\Gamma) = \{ \Box_n(p \supset q), \Box_n(r \supset q) \} \\ U_7^t(\Gamma) = \emptyset
```

Definition

 $\langle A, B \rangle_t \in \Omega_t, \, \langle A, B \rangle_{pt_i} \in \Omega_{pt_i} \text{ and } \langle A, B \rangle_{pp_i} \in \Omega_{pp_i}$



Definition

 $\langle A, B \rangle_t \in \Omega_t, \, \langle A, B \rangle_{\it pt_i} \in \Omega_{\it pt_i} \text{ and } \langle A, B \rangle_{\it pp_i} \in \Omega_{\it pp_i}$

Example				
$1 \Box_n(p \supset q)$ $2 \Box_n \diamond_e(p \land q)$ $3 \Box_n(r \supset q)$ $4 \Box_n \diamond_e \diamond_e(r \land q)$ $5 q$	–;PREM –;PREM –;PREM –;PREM –;PREM	0 0 0 0 0		

Set of Unreliable Formulas

 $U^{bk}_5(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\}$

Definition

 $\langle A, B \rangle_t \in \Omega_t, \, \langle A, B \rangle_{pt_i} \in \Omega_{pt_i} \text{ and } \langle A, B \rangle_{pp_i} \in \Omega_{pp_i}$

Example		
$1 \Box_n(p \supset q)$ $2 \Box_n \Diamond_e(p \land q)$ $3 \Box_n(r \supset q)$ $4 \Box_n \Diamond_e \Diamond_e(r \land q)$ $5 q$ $6 p$ $7 r$	-;PREM -;PREM -;PREM -;PREM 1,2,5;RC 3,4,5;RC	$ \begin{cases} \emptyset \\ \emptyset \\ \emptyset \\ \emptyset \\ \{ \Box_{e} q, \Box_{n} q, \langle p, q \rangle_{pt_{1}} \} \\ \{ \Box_{e} q, \Box_{n} q, \langle r, q \rangle_{pt_{2}} \} \end{cases} $

Set of Unreliable Formulas $U_7^{bk}(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\}$

Definition

 $\langle A, B \rangle_t \in \Omega_t, \, \langle A, B \rangle_{\rho t_i} \in \Omega_{\rho t_i} \text{ and } \langle A, B \rangle_{\rho \rho_i} \in \Omega_{\rho \rho_i}$

E	Example				
1 2 3 4 5 6 7 8 9	$ \begin{array}{c} \Box_n(p \supset q) \\ \Box_n \Diamond_e(p \land q) \\ \Box_n(r \supset q) \\ \Box_n \diamond_e \diamond_e(r \land q) \\ q \\ p \\ r \\ \langle p, q \rangle_{pt_1} \lor \langle r \land \neg p, q \rangle_{pp_2} \\ \langle r, q \rangle_{pt_2} \lor \langle p \land \neg r, q \rangle_{pp_1} \end{array} $	-;PREM -;PREM -;PREM -;PREM 1,2,5;RC 3,4,5;RC 1,2,3,4,5;RC 1,2,3,4,5;RC			

Set of Unreliable Formulas

 $U_9^{bk}(\Gamma) = \{ \Box_n(p \supset q), \Box_n(r \supset q) \}$

Definition

 $\langle \boldsymbol{A}, \boldsymbol{B} \rangle_t \in \Omega_t, \, \langle \boldsymbol{A}, \boldsymbol{B} \rangle_{\textit{pt}_i} \in \Omega_{\textit{pt}_i} \text{ and } \langle \boldsymbol{A}, \boldsymbol{B} \rangle_{\textit{pp}_i} \in \Omega_{\textit{pp}_i}$

Example						
1 2 3 4 5 6 7 8 9 10 11	$ \begin{array}{c} \Box_{n}(p \supset q) \\ \Box_{n} \diamond_{e}(p \land q) \\ \Box_{n}(r \supset q) \\ \Box_{n} \diamond_{e} \diamond_{e}(r \land q) \\ q \\ p \\ r \\ \langle p, q \rangle_{pt_{1}} \lor \langle r \land \neg p, q \rangle_{pp_{2}} \\ \langle r, q \rangle_{pt_{2}} \lor \langle p \land \neg r, q \rangle_{pp_{1}} \\ \langle r \land \neg p, q \rangle_{pp_{2}} \\ \langle r, q \rangle_{pt_{2}} \end{array} $	-;PREM -;PREM -;PREM -;PREM 1, 2, 5;RC 3, 4, 5;RC 1,2,3,4,5;RC 1,2,3,4,5;RC 1,2,3,4,5;RC 8;RC 9;RC				

Set of Unreliable Formulas
$$U_{11}^{bk}(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\}$$
 $U_{11}^{bl_2}(\Gamma) = \{\langle r, q \rangle_{pl_2}\}$ $U_{11}^{pp_2}(\Gamma) = \{\langle r \land \neg p, q \rangle_{pp_2}\}$

Definition

 $\langle \boldsymbol{A}, \boldsymbol{B} \rangle_t \in \Omega_t, \, \langle \boldsymbol{A}, \boldsymbol{B} \rangle_{\textit{pt}_i} \in \Omega_{\textit{pt}_i} \text{ and } \langle \boldsymbol{A}, \boldsymbol{B} \rangle_{\textit{pp}_i} \in \Omega_{\textit{pp}_i}$

Example						
1 2 3 4 5 6 7 8 9 10 11	$ \begin{array}{c} \Box_n(p \supset q) \\ \Box_n \diamond_e(p \land q) \\ \Box_n(r \supset q) \\ \Box_n \diamond_e \diamond_e(r \land q) \\ q \\ p \\ r \\ \langle p, q \rangle_{pt_1} \lor \langle r \land \neg p, q \rangle_{pp_2} \\ \langle r, q \rangle_{pt_2} \lor \langle p \land \neg r, q \rangle_{pp_1} \\ \langle r \land \neg p, q \rangle_{pp_2} \\ \langle r, q \rangle_{pt_2} \end{array} $	-;PREM -;PREM -;PREM -;PREM 1,2,5;RC 3,4,5;RC 1,2,3,4,5;RC 1,2,3,4,5;RC 1,2,3,4,5;RC 8;RC 9;RC		×		

Set of Unreliable Formulas

$$U_{11}^{bk}(\Gamma) = \{\Box_n(p \supset q), \Box_n(r \supset q)\}$$

$$U_{11}^{pp_2}(\Gamma) = \{\langle r \land \neg p, q \rangle_{pp_2}\}$$

$$U_{11}^{pp_2}(\Gamma) = \{\langle r \land \neg p, q \rangle_{pp_2}\}$$

Further Research

Finetuning of

• the adaptive logics for prioritized abduction.

Development of

- adaptive logics for abduction based on inconsistent background knowledge, and of
- adaptive logics that combine abduction with induction.



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